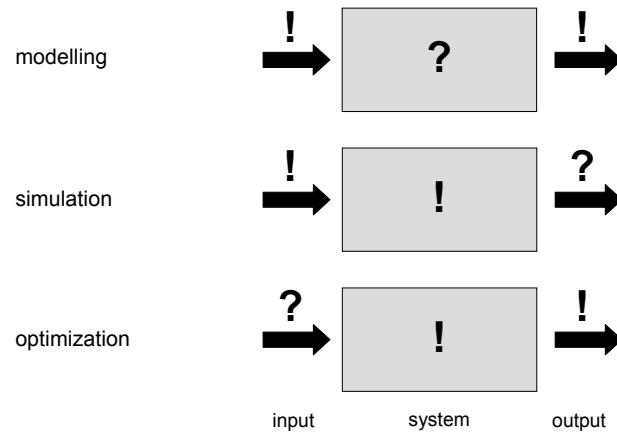


Computational Intelligence

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Prof. Dr. Günter Rudolph
 Lehrstuhl für Algorithm Engineering (LS 11)
 Fakultät für Informatik
 TU Dortmund

- Evolutionary Algorithms
 - Optimization Basics
 - EA Basics



given:

objective function $f: X \rightarrow \mathbb{R}$

feasible region X (= nonempty set)

objective: find solution with *minimal* or *maximal* value!

optimization problem:

find $x^* \in X$ such that $f(x^*) = \min\{f(x) : x \in X\}$

x^* **global solution**

$f(x^*)$ **global optimum**

note:

$\max\{f(x) : x \in X\} = -\min\{-f(x) : x \in X\}$

local solution $x^* \in X$:

$$\forall x \in N(x^*): f(x^*) \leq f(x)$$

neighborhood of x^* =
bounded subset of X

} if x^* local solution then
 $f(x^*)$ **local optimum / minimum**

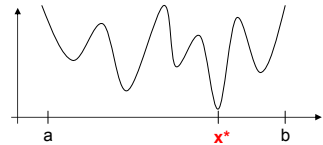
example: $X = \mathbb{R}^n, N_\epsilon(x^*) = \{x \in X: \|x - x^*\|_2 \leq \epsilon\}$

remark:

evidently, every global solution / optimum is also local solution / optimum;
the reverse is wrong in general!

example:

$f: [a,b] \rightarrow \mathbb{R}$, global solution at x^*



What makes optimization difficult?

some causes:

- local optima (is it a global optimum or not?)
- constraints (ill-shaped feasible region)
- non-smoothness (weak causality) → strong causality needed!
- discontinuities (⇒ nondifferentiability, no gradients)
- lack of knowledge about problem (⇒ black / gray box optimization)

$f(x) = a_1 x_1 + \dots + a_n x_n \rightarrow \max!$ with $x_i \in \{0,1\}, a_i \in \mathbb{R}$

add constraint $g(x) = b_1 x_1 + \dots + b_n x_n \leq b$

⇒ $x_i^* = 1$ if $a_i > 0$

⇒ NP-hard

add capacity constraint to TSP ⇒ CVRP

⇒ still harder

When using which optimization method?

mathematical algorithms

- problem explicitly specified
- problem-specific solver available
- problem well understood
- resources for designing algorithm affordable
- solution with proven quality required

⇒ **don't apply EAs**

randomized search heuristics

- problem given by black / gray box
- no problem-specific solver available
- problem poorly understood
- insufficient resources for designing algorithm
- solution with satisfactory quality sufficient

⇒ **EAs worth a try**

idea: using **biological evolution** as **metaphor** and as **pool of inspiration**

⇒ interpretation of biological evolution as iterative method of improvement

feasible solution $x \in X = S_1 \times \dots \times S_n$ = chromosome of **individual**

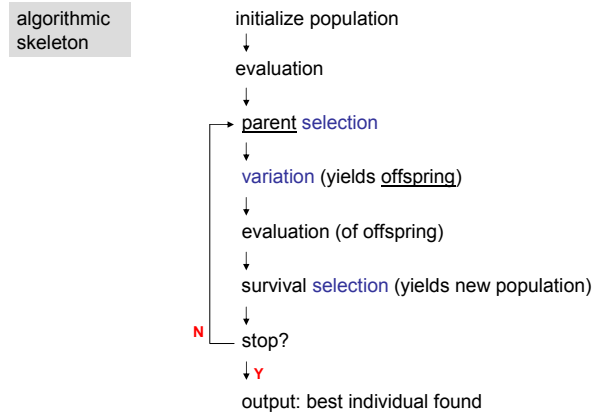
multiset of feasible solutions = **population**: multiset of individuals

objective function $f: X \rightarrow \mathbb{R}$ = **fitness function**

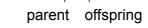
often: $X = \mathbb{R}^n, X = \mathbb{B}^n = \{0,1\}^n, X = \mathbb{P}_n = \{\pi : \pi \text{ is permutation of } \{1,2,\dots,n\}\}$

also: combinations like $X = \mathbb{R}^n \times \mathbb{B}^p \times \mathbb{P}_q$ or non-cartesian sets

⇒ structure of feasible region / search space defines **representation** of individual



Specific example: (1+1)-EA in \mathbb{B}^n for minimizing some $f: \mathbb{B}^n \rightarrow \mathbb{R}$
 population size = 1, number of offspring = 1, selects best from 1+1 individuals



1. initialize $X^{(0)} \in \mathbb{B}^n$ uniformly at random, set $t = 0$
2. evaluate $f(X^{(0)})$
3. select parent: $Y = X^{(0)}$ no choice, here
4. variation: flip each bit of Y independently with probability $p_m = 1/n$
5. evaluate $f(Y)$
6. selection: if $f(Y) \leq f(X^{(0)})$ then $X^{(t+1)} = Y$ else $X^{(t+1)} = X^{(t)}$
7. if not stopping then $t = t+1$, continue at (3)

Selection

- (a) select parents that generate offspring → selection for reproduction
- (b) select individuals that proceed to next generation → selection for survival

necessary requirements:

- selection steps must not favor worse individuals
- one selection step may be neutral (e.g. select uniformly at random)
- at least one selection step must favor better individuals

typically : selection only based on fitness values $f(x)$ of individuals
 seldom : additionally based on individuals' chromosomes x (→ maintain diversity)

Selection methods

population $P = (x_1, x_2, \dots, x_\mu)$ with μ individuals

two approaches:

1. repeatedly select individuals from population with replacement
2. rank individuals somehow and choose those with best ranks (no replacement)

• **uniform / neutral selection**

choose index i with probability $1/\mu$

• **fitness-proportional selection**

choose index i with probability $s_i = \frac{f(x_i)}{\sum_{x \in P} f(x)}$

problems: $f(x) > 0$ for all $x \in X$ required $\Rightarrow g(x) = \exp(f(x)) > 0$

but already sensitive to additive shifts $g(x) = f(x) + c$

almost deterministic if large differences, almost uniform if small differences



Selection methods

population $P = (x_1, x_2, \dots, x_\mu)$ with μ individuals

- **rank-proportional selection**

order individuals according to their fitness values
 assign ranks
 fitness-proportional selection based on ranks

⇒ avoids all problems of fitness-proportional selection
 but: best individual has only small selection advantage (can be lost!)

outdated!

- **k-ary tournament selection**

draw k individuals uniformly at random (typically with replacement) from P
 choose individual with best fitness (break ties at random)

⇒ has all advantages of rank-based selection and
 probability that best individual does not survive: $\left(1 - \frac{1}{\mu}\right)^{k\mu} \approx e^{-k}$

Selection methods without replacement

population $P = (x_1, x_2, \dots, x_\mu)$ with μ parents and

population $Q = (y_1, y_2, \dots, y_\lambda)$ with λ offspring

- **(μ, λ) -selection** or **truncation selection on offspring** or **comma-selection**

rank λ offspring according to their fitness
 select μ offspring with best ranks

⇒ best individual may get lost, $\lambda \geq \mu$ required

- **$(\mu+\lambda)$ -selection** or **truncation selection on parents + offspring** or **plus-selection**

merge λ offspring and μ parents
 rank them according to their fitness
 select μ individuals with best ranks

⇒ best individual survives for sure