

# Computational Intelligence

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Three tasks:

1. Choice of an appropriate problem representation.
2. Choice / design of variation operators acting in problem representation.
3. Choice of strategy parameters (includes initialization).

ad 1) different "schools":

- (a) operate on binary representation and define genotype/phenotype mapping
  - + can use standard algorithm
  - mapping may induce unintentional bias in search
- (b) no doctrine: use "most natural" representation
  - must design variation operators for specific representation
  - + if design done properly then no bias in search

ad 2) design guidelines for variation operators

**a) reachability**

every  $x \in X$  should be reachable from arbitrary  $x_0 \in X$   
after finite number of repeated variations with positive probability bounded from 0

**b) unbiasedness**

unless having gathered knowledge about problem  
variation operator should not favor particular subsets of solutions  
⇒ formally: maximum entropy principle

**c) control**

variation operator should have parameters affecting shape of distributions;  
known from theory: weaken variation strength when approaching optimum

ad 2) design guidelines for variation operators **in practice**

binary search space  $X = \mathbb{B}^n$

variation by k-point or uniform crossover and subsequent mutation

**a) reachability:**

regardless of the output of crossover  
we can move from  $x \in \mathbb{B}^n$  to  $y \in \mathbb{B}^n$  in 1 step with probability

$$p(x, y) = p_m^{H(x,y)} (1 - p_m)^{n-H(x,y)} > 0$$

where  $H(x, y)$  is Hamming distance between  $x$  and  $y$ .

Since  $\min\{p(x, y): x, y \in \mathbb{B}^n\} = \delta > 0$  we are done.

b) *unbiasedness*

don't prefer any direction or subset of points without reason

⇒ use maximum entropy distribution for sampling!

properties:

- distributes probability mass as uniform as possible
- additional knowledge can be included as constraints:  
→ under given constraints sample as uniform as possible

Formally:**Definition:**

Let  $X$  be discrete random variable (r.v.) with  $p_k = P\{X = x_k\}$  for some index set  $K$ .  
The quantity

$$H(X) = - \sum_{k \in K} p_k \log p_k$$

is called the **entropy of the distribution** of  $X$ . If  $X$  is a continuous r.v. with p.d.f.  $f_X(\cdot)$  then the entropy is given by

$$H(X) = \int_{-\infty}^{\infty} f_X(x) \log f_X(x) dx$$

The distribution of a random variable  $X$  for which  $H(X)$  is maximal is termed a **maximum entropy distribution**. ■

**Knowledge available:**

Discrete distribution with support  $\{x_1, x_2, \dots, x_n\}$  with  $x_1 < x_2 < \dots < x_n < \infty$

$$p_k = P\{X = x_k\}$$

⇒ leads to nonlinear constrained optimization problem:

$$\begin{aligned} - \sum_{k=1}^n p_k \log p_k &\rightarrow \max! \\ \text{s.t. } \sum_{k=1}^n p_k &= 1 \end{aligned}$$

solution: via Lagrange (find stationary point of Lagrangian function)

$$L(p, a) = - \sum_{k=1}^n p_k \log p_k + a \left( \sum_{k=1}^n p_k - 1 \right)$$

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partial derivatives:

$$\frac{\partial L(p, a)}{\partial p_k} = -1 - \log p_k + a \stackrel{!}{=} 0 \quad \Rightarrow \quad p_k \stackrel{!}{=} e^{a-1}$$

$$\frac{\partial L(p, a)}{\partial a} = \sum_{k=1}^n p_k - 1 \stackrel{!}{=} 0$$

$$\Rightarrow \sum_{k=1}^n p_k = \sum_{k=1}^n e^{a-1} = n e^{a-1} \stackrel{!}{=} 1 \quad \Leftrightarrow \quad e^{a-1} = \frac{1}{n}$$

$p_k = \frac{1}{n}$   
**uniform distribution**

Knowledge available:

Discrete distribution with support  $\{1, 2, \dots, n\}$  with  $p_k = P\{X = k\}$  and  $E[X] = \nu$

⇒ leads to nonlinear constrained optimization problem:

$$-\sum_{k=1}^n p_k \log p_k \rightarrow \max!$$

s.t.  $\sum_{k=1}^n p_k = 1$  and  $\sum_{k=1}^n k p_k = \nu$

solution: via Lagrange (find stationary point of Lagrangian function)

$$L(p, a, b) = -\sum_{k=1}^n p_k \log p_k + a \left( \sum_{k=1}^n p_k - 1 \right) + b \left( \sum_{k=1}^n k \cdot p_k - \nu \right)$$

$$L(p, a, b) = -\sum_{k=1}^n p_k \log p_k + a \left( \sum_{k=1}^n p_k - 1 \right) + b \left( \sum_{k=1}^n k \cdot p_k - \nu \right)$$

partial derivatives:

$$\frac{\partial L(p, a, b)}{\partial p_k} = -1 - \log p_k + a + b k \stackrel{!}{=} 0 \Rightarrow p_k = e^{a-1+bk}$$

$$\frac{\partial L(p, a, b)}{\partial a} = \sum_{k=1}^n p_k - 1 \stackrel{!}{=} 0$$

$$\frac{\partial L(p, a, b)}{\partial b} = \sum_{k=1}^n k p_k - \nu \stackrel{!}{=} 0 \Leftrightarrow \sum_{k=1}^n p_k = e^{a-1} \sum_{k=1}^n (e^b)^k \stackrel{!}{=} 1$$

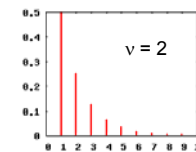
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$$\Rightarrow e^{a-1} = \frac{1}{\sum_{k=1}^n (e^b)^k} \Rightarrow p_k = e^{a-1+bk} = \frac{(e^b)^k}{\sum_{i=1}^n (e^b)^i}$$

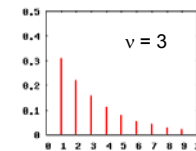
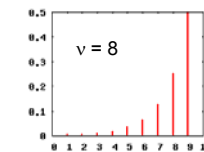
$$\Rightarrow \text{discrete Boltzmann distribution } p_k = \frac{q^k}{\sum_{i=1}^n q^i} \quad (q = e^b)$$

⇒ value of q depends on  $\nu$  via third condition: (\*)

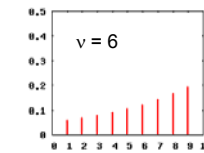
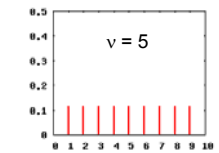
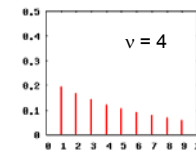
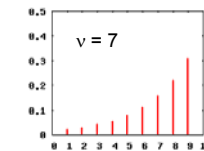
$$\sum_{k=1}^n k p_k = \frac{\sum_{k=1}^n k q^k}{\sum_{i=1}^n q^i} = \frac{1 - (n+1)q^n + nq^{n+1}}{(1-q)(1-q^n)} \stackrel{!}{=} \nu$$



Boltzmann distribution  
(n = 9)



specializes to uniform  
distribution if  $\nu = 5$   
(as expected)



**Knowledge available:**

Discrete distribution with support  $\{1, 2, \dots, n\}$  with  $E[X] = \nu$  and  $V[X] = \eta^2$

⇒ leads to nonlinear constrained optimization problem:

$$-\sum_{k=1}^n p_k \log p_k \rightarrow \max!$$

$$\text{s.t. } \sum_{k=1}^n p_k = 1 \quad \text{and} \quad \sum_{k=1}^n k p_k = \nu \quad \text{and} \quad \sum_{k=1}^n (k - \nu)^2 p_k = \eta^2$$

solution: in principle, via Lagrange (find stationary point of Lagrangian function)

but very complicated analytically, if possible at all

⇒ consider special cases only

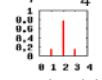
**note:** constraints are linear equations in  $p_k$

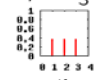
**Special case:**  $n = 3$  and  $E[X] = 2$  and  $V[X] = \eta^2$

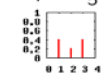
Linear constraints uniquely determine distribution:

$$\begin{array}{l} \text{I. } p_1 + p_2 + p_3 = 1 \\ \text{II. } p_1 + 2p_2 + 3p_3 = 2 \\ \text{III. } p_1 + 0 + p_3 = \eta^2 \end{array} \quad \left. \begin{array}{l} p_1 = \frac{\eta^2}{2} \\ p_3 = \frac{\eta^2}{2} \end{array} \right\} \begin{array}{l} \text{insertion in III.} \\ \text{II-I: } p_2 + 2p_3 = 1 \\ \text{I-III: } p_2 = 1 - \eta^2 \end{array}$$

$$\Rightarrow p = \left( \frac{\eta^2}{2}, 1 - \eta^2, \frac{\eta^2}{2} \right)$$

$\eta^2 = \frac{1}{4}$   
  
 unimodal

$\eta^2 = \frac{2}{3}$   
  
 uniform

$\eta^2 = \frac{4}{5}$   
  
 bimodal

**Knowledge available:**

Discrete distribution with unbounded support  $\{0, 1, 2, \dots\}$  and  $E[X] = \nu$

⇒ leads to infinite-dimensional nonlinear constrained optimization problem:

$$-\sum_{k=0}^{\infty} p_k \log p_k \rightarrow \max!$$

$$\text{s.t. } \sum_{k=0}^{\infty} p_k = 1 \quad \text{and} \quad \sum_{k=0}^{\infty} k p_k = \nu$$

solution: via Lagrange (find stationary point of Lagrangian function)

$$L(p, a, b) = -\sum_{k=0}^{\infty} p_k \log p_k + a \left( \sum_{k=0}^{\infty} p_k - 1 \right) + b \left( \sum_{k=0}^{\infty} k \cdot p_k - \nu \right)$$

$$L(p, a, b) = -\sum_{k=0}^{\infty} p_k \log p_k + a \left( \sum_{k=0}^{\infty} p_k - 1 \right) + b \left( \sum_{k=0}^{\infty} k \cdot p_k - \nu \right)$$

partial derivatives:

$$\frac{\partial L(p, a, b)}{\partial p_k} = -1 - \log p_k + a + b k \stackrel{!}{=} 0 \quad \Rightarrow p_k = e^{a-1+bk}$$

$$\frac{\partial L(p, a, b)}{\partial a} = \sum_{k=0}^{\infty} p_k - 1 \stackrel{!}{=} 0$$

$$\frac{\partial L(p, a, b)}{\partial b} \stackrel{(*)}{=} \sum_{k=0}^{\infty} k p_k - \nu \stackrel{!}{=} 0 \quad \Leftrightarrow \sum_{k=0}^{\infty} p_k = e^{a-1} \sum_{k=0}^{\infty} (e^b)^k \stackrel{!}{=} 1$$

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$$\Rightarrow e^{a-1} = \frac{1}{\sum_{k=0}^{\infty} (e^b)^k} \quad \Rightarrow p_k = e^{a-1+bk} = \frac{(e^b)^k}{\sum_{i=0}^{\infty} (e^b)^i}$$

set  $q = e^b$  and insists that  $q < 1 \Rightarrow \sum_{k=0}^{\infty} q^k = \frac{1}{1-q}$  ↑ insert

$\Rightarrow p_k = (1-q)q^k$  for  $k = 0, 1, 2, \dots$  **geometrical distribution**

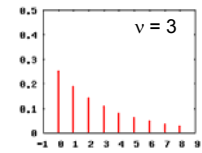
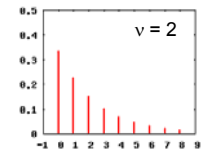
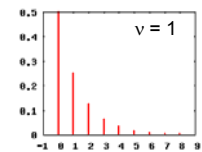
it remains to specify  $q$ ; to proceed recall that  $\sum_{k=0}^{\infty} k q^k = \frac{q}{(1-q)^2}$

$\Rightarrow$  value of  $q$  depends on  $\nu$  via third condition: ( $\star$ )

$$\sum_{k=0}^{\infty} k p_k = \frac{\sum_{k=0}^{\infty} k q^k}{\sum_{i=0}^{\infty} q^i} = \frac{q}{1-q} \stackrel{!}{=} \nu$$

$\Rightarrow q = \frac{\nu}{\nu+1} = 1 - \frac{1}{\nu+1}$

$\Rightarrow p_k = \frac{1}{\nu+1} \left(1 - \frac{1}{\nu+1}\right)^k$



**geometrical distribution**  
with  $E[x] = \nu$

$p_k$  only shown  
for  $k = 0, 1, \dots, 8$

