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Computational Intelligence

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Plan for Today

- Single-Layer Perceptron
  - Accelerated Learning
  - Online- vs. Batch-Learning
- Multi-Layer-Perceptron
  - Model
  - Backpropagation

Single-Layer Perceptron (SLP)

Acceleration of Perceptron Learning

<u>Assumption:</u> $x \in \{ 0, 1 \}^n \;\Rightarrow\; ||x|| \geq 1$ for all $x \neq (0, ..., 0)'$

If classification incorrect, then $w'x < 0$.

Consequently, size of error is just $\delta = -w'x > 0$.

$\Rightarrow w_{t+1} = w_t + (\delta + \varepsilon)\, x$ for $\varepsilon > 0$ (small) corrects error in a <u>*single*</u> step, since

$$
\begin{aligned}
w'_{t+1}x &= (w_t + (\delta + \varepsilon)\, x)'\, x \\
&= \underbrace{w'_t\, x} + (\delta + \varepsilon)\, x'x \\
&= -\delta + \delta\, ||x||^2 + \varepsilon\, ||x||^2 \\
&= \underbrace{\delta\, (||x||^2 - 1)}_{\geq 0} + \underbrace{\varepsilon\, ||x||^2}_{> 0} \;>\; 0 \quad ☑
\end{aligned}
$$

Single-Layer Perceptron (SLP)

Generalization:

<u>Assumption:</u> $x \in \mathbb{R}^n \qquad \Rightarrow ||x|| > 0$ for all $x \neq (0, ..., 0)'$

as before: $w_{t+1} = w_t + (\delta + \varepsilon)\, x$ for $\varepsilon > 0$ (small) and $\delta = -\,w'_t\, x > 0$

$$
\Rightarrow \quad w'_{t+1}x = \underbrace{\delta\, (||x||^2 - 1)}_{<\,0 \text{ possible!}} + \underbrace{\varepsilon\, ||x||^2}_{> 0}
$$

<u>Idea:</u> Scaling of data does not alter classification task!

Let $\ell = \min \{ ||\, x\, || : x \in B \} > 0$

Set $\hat{x} = \dfrac{x}{\ell} \quad \Rightarrow$ set of scaled examples $\hat{B}$

$\Rightarrow ||\,\hat{x}\,|| \geq 1 \quad \Rightarrow \quad ||\,\hat{x}\,||^2 - 1 \geq 0 \quad \Rightarrow \quad w'_{t+1}\, \hat{x} > 0$ ☑

There exist numerous variants of Perceptron Learning Methods.

Theorem: (Duda & Hart 1973)

If rule for correcting weights is $w_{t+1} = w_t + \gamma_t x$ (if $w'_t x < 0$)

1. $\forall t \geq 0 : \gamma_t \geq 0$
2. $\sum_{t=0}^{\infty} \gamma_t = \infty$
3. $\lim_{m\to\infty} \frac{\sum_{t=0}^{m} \gamma_t^2}{\left(\sum_{t=0}^{m} \gamma_t\right)^2} = 0$

then $w_t \to w^*$ for $t \to \infty$ with $\forall x'w^* > 0$. ■

e.g.: $\gamma_t = \gamma > 0$ or $\gamma_t = \gamma / (t+1)$ for $\gamma > 0$

as yet: *Online Learning*

→ Update of weights after each training pattern (if necessary)

now: *Batch Learning*

→ Update of weights only after test of all training patterns

→ Update rule:

$$w_{t+1} = w_t + \gamma \sum_{\substack{w'_t x < 0 \\ x \in B}} x \qquad (\gamma > 0)$$

vague assessment in literature:

- advantage : „usually faster“
- disadvantage : „needs more memory“ ← just a single vector!

find weights by means of optimization

Let $F(w) = \{ x \in B : w'x < 0 \}$ be the set of patterns incorrectly classified by weight w.

Objective function: $f(w) = -\sum_{x \in F(w)} w'x \to \min!$

Optimum: $f(w) = 0$ iff $F(w)$ is empty

Possible approach: *gradient method*

$$\boxed{w_{t+1} = w_t - \gamma \nabla f(w_t) \qquad (\gamma > 0)}$$

converges to a local minimum (dep. on w_0)

Gradient method

$w_{t+1} = w_t - \gamma \nabla f(w_t)$

Gradient points in direction of steepest ascent of function $f(\cdot)$

Gradient $\nabla f(w) = \left(\frac{\partial f(w)}{\partial w_1}, \frac{\partial f(w)}{\partial w_2}, \ldots, \frac{\partial f(w)}{\partial w_n} \right)$

Caution: Indices i of w_i here denote components of vektor w; they are **not** the iteration counters!

$$\frac{\partial f(w)}{\partial w_i} = -\frac{\partial}{\partial w_i} \sum_{x \in F(w)} w'x = -\frac{\partial}{\partial w_i} \sum_{x \in F(w)} \sum_{j=1}^{n} w_j \cdot x_j$$

$$= -\sum_{x \in F(w)} \underbrace{\frac{\partial}{\partial w_i} \left(\sum_{j=1}^{n} w_j \cdot x_j \right)}_{x_i} = -\sum_{x \in F(w)} x_i$$

Gradient method

thus:

gradient $\nabla f(w) = \left(\frac{\partial f(w)}{\partial w_1}, \frac{\partial f(w)}{\partial w_2}, \ldots, \frac{\partial f(w)}{\partial w_n} \right)'$

$$= \left(-\sum_{x \in F(w)} x_1, -\sum_{x \in F(w)} x_2, \ldots, -\sum_{x \in F(w)} x_n \right)'$$

$$= -\sum_{x \in F(w)} x$$

$$\Rightarrow \quad w_{t+1} = w_t + \gamma \sum_{x \in F(w_t)} x$$

gradient method ⇔ batch learning

How difficult is it

(a) to find a separating hyperplane, provided it exists?

(b) to decide, that there is no separating hyperplane?

Let $B = P \cup \{ -x : x \in N \}$ (only positive examples), $w_i \in \mathbb{R}$, $\theta \in \mathbb{R}$, $|B| = m$

For every example $x_i \in B$ should hold:

$x_{i1} w_1 + x_{i2} w_2 + \ldots + x_{in} w_n \geq \theta$ → trivial solution $w_i = \theta = 0$ to be excluded!

Therefore additionally: $\eta \in \mathbb{R}$

$x_{i1} w_1 + x_{i2} w_2 + \ldots + x_{in} w_n - \theta - \eta \geq 0$

Idea: η maximize → if $\eta^* > 0$, then solution found

Matrix notation:

$$A = \begin{pmatrix} x_1' & -1 & -1 \\ x_2' & -1 & -1 \\ \vdots & \vdots & \vdots \\ x_m' & -1 & -1 \end{pmatrix} \qquad z = \begin{pmatrix} w \\ \theta \\ \eta \end{pmatrix}$$

Linear Programming Problem:

$f(z_1, z_2, \ldots, z_n, z_{n+1}, z_{n+2}) = z_{n+2} \rightarrow$ max!

s.t. $Az \geq 0$

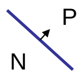
calculated by e.g. Kamarkar-algorithm in **polynomial time**

If $z_{n+2} = \eta > 0$, then weights and threshold are given by z.

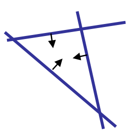
Otherwise separating hyperplane does not exist!

What can be achieved by adding a layer?

- Single-layer perceptron (SLP)
  ⇒ Hyperplane separates space in two subspaces

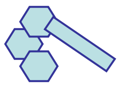


- Two-layer perceptron
  ⇒ arbitrary convex sets can be separated



connected by AND gate in 2nd layer

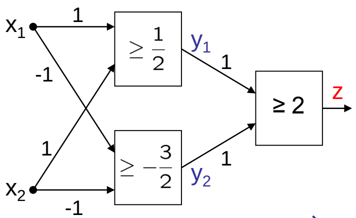
- Three-layer perceptron
  ⇒ arbitrary sets can be separated (depends on number of neurons)-
  several convex sets representable by 2nd layer,
  these sets can be combined in 3rd layer



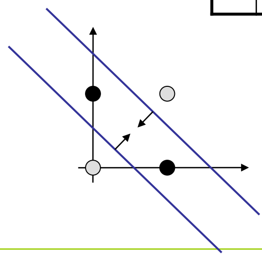
convex sets of 2nd layer connected by OR gate in 3rd layer

⇒ more than 3 layers not necessary!

XOR with 3 neurons in 2 steps

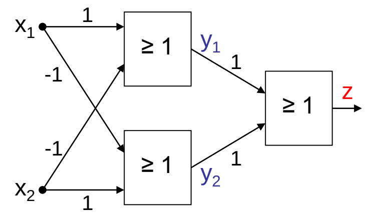


x_1	x_2	y_1	y_2	z
0	0	0	1	0
0	1	1	1	1
1	0	1	1	1
1	1	1	0	0



convex set

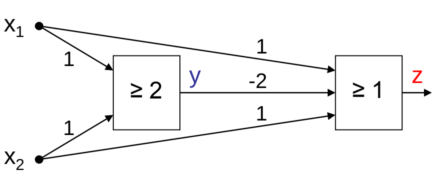
XOR with 3 neurons in 2 layers



x_1	x_2	y_1	y_2	z
0	0	0	0	0
0	1	0	1	1
1	0	1	0	1
1	1	0	0	0

without AND gate in 2nd layer

XOR can be realized with only 2 neurons!



x_1	x_2	y	-2y	x_1-2y+x_2	z
0	0	0	0	0	0
0	1	0	0	1	1
1	0	0	0	1	1
1	1	1	-2	0	0

BUT: this is not a layered network (no MLP) !

Evidently:

MLPs deployable for addressing significantly more difficult problems than SLPs!

But:

How can we adjust all these weights and thresholds?

Is there an efficient learning algorithm for MLPs?

History:

Unavailability of efficient learning algorithm for MLPs was a brake shoe ...

... until **Rumelhart, Hinton** and **Williams (1986): Backpropagation**

Actually proposed by **Werbos (1974)**

... but unknown to ANN researchers (was PhD thesis)

Quantification of classification error of MLP

- Total Sum Squared Error (TSSE)

$$f(w) = \sum_{x \in B} \| \underbrace{g(w;x)}_{\text{output of net for weights w and input x}} - \underbrace{g^*(x)}_{\text{target output of net for input x}} \|^2$$

- Total Mean Squared Error (TMSE)

$$f(w) = \frac{1}{|B| \cdot \ell} \sum_{x \in B} \| g(w;x) - g^*(x) \|^2 = \underbrace{\frac{1}{|B| \cdot \ell}}_{\textit{const.}} \cdot \text{ TSSE}$$

training patters

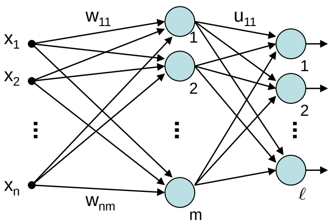
output neurons

⇒ leads to same solution as TSSE

Learning algorithms for Multi-Layer-Perceptron (here: 2 layers)

idea: minimize error!

$f(w_t, u_t)$ = TSSE → min!



Gradient method

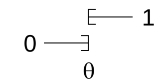
$$\boxed{\begin{aligned} u_{t+1} &= u_t - \gamma \nabla_u f(w_t, u_t) \\ w_{t+1} &= w_t - \gamma \nabla_w f(w_t, u_t) \end{aligned}}$$

$$a(x) = \begin{cases} 1 & \text{if } x > \theta \\ 0 & \text{otherwise} \end{cases}$$

BUT:

f(w, u) cannot be differentiated!

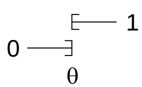
Why? → Discontinuous activation function a(.) in neuron!

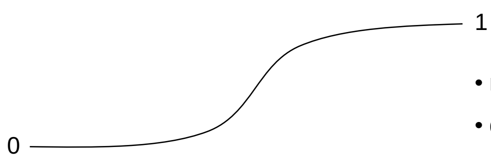


idea: find **smooth** activation function similar to original function !

Learning algorithms for Multi-Layer-Perceptron (here: 2 layers)

good idea: sigmoid activation function (instead of signum function)





- monotone increasing
- differentiable
- non-linear
- output ∈ [0,1] instead of ∈ { 0, 1 }
- threshold θ integrated in activation function

e.g.:

- $a(x) = \frac{1}{1+e^{-x}}$ $\quad a'(x) = a(x)(1-a(x))$
- $a(x) = \tanh(x)$ $\quad a'(x) = (1-a^2(x))$

values of derivatives directly determinable from function values

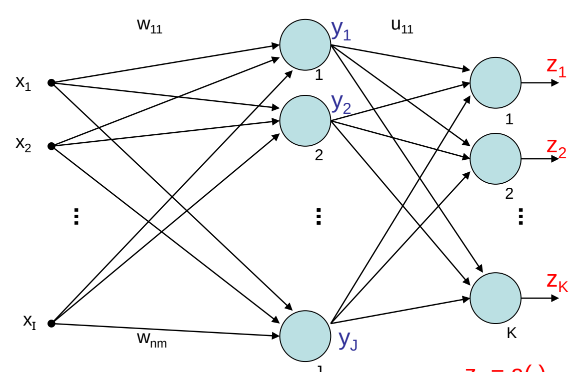
Learning algorithms for Multi-Layer-Perceptron (here: 2 layers)

Gradient method

$f(w_t, u_t)$ = TSSE

$u_{t+1} = u_t - \gamma \nabla_u f(w_t, u_t)$

$w_{t+1} = w_t - \gamma \nabla_w f(w_t, u_t)$



x_i : inputs

y_j : values after first layer

z_k: values after second layer

$y_j = h(\cdot)$

$z_k = a(\cdot)$

$$y_j = h\left(\sum_{i=1}^{I} w_{ij}\cdot x_i\right) = h(w_j' x)$$

output of neuron j after 1st layer

$$z_k = a\left(\sum_{j=1}^{J} u_{jk}\cdot y_j\right) = a(u_k' y)$$

output of neuron k after 2nd layer

$$= a\left(\sum_{j=1}^{J} u_{jk}\cdot h\left(\sum_{i=1}^{I} w_{ij}\cdot x_i\right)\right)$$

error of input x:

$$f(w,u;x) = \sum_{k=1}^{K}(z_k(x) - z_k^*(x))^2 = \sum_{k=1}^{K}(z_k - z_k^*)^2$$

output of net target output for input x

error for input x and target output z*:

$$f(w,u;x,z^*) = \sum_{k=1}^{K}\left[\underbrace{a\left(\sum_{j=1}^{J} u_{jk}\cdot \underbrace{h\left(\overbrace{\sum_{i=1}^{I} w_{ij}\cdot x_i}^{w_j' x}\right)}_{y_j}\right)}_{z_k} - z_k^*(x)\right]^2$$

total error for all training patterns (x, z*) ∈ B:

$$f(w,u) = \sum_{(x,z^*)\in B} f(w,u;x,z^*)$$ (TSSE)

gradient of total error:

$$\nabla f(w,u) = \sum_{(x,z^*)\in B} \nabla f(w,u;x,z^*)$$

vector of partial derivatives w.r.t. weights u_{jk} and w_{ij}

thus:

$$\frac{\partial f(w,u)}{\partial u_{jk}} = \sum_{(x,z^*)\in B}\frac{\partial f(w,u;x,z^*)}{\partial u_{jk}}$$

and

$$\frac{\partial f(w,u)}{\partial w_{ij}} = \sum_{(x,z^*)\in B}\frac{\partial f(w,u;x,z^*)}{\partial w_{ij}}$$

assume: $a(x) = \dfrac{1}{1+e^{-x}} \Rightarrow \dfrac{d\,a(x)}{dx} = a'(x) = a(x)\cdot(1-a(x))$

and: $h(x) = a(x)$

chain rule of differential calculus:

$$[\,p(q(x))\,]' = \underbrace{p'(q(x))}_{\text{outer derivative}}\cdot\underbrace{q'(x)}_{\text{inner derivative}}$$

$$f(w,u;x,z^*) \;=\; \sum_{k=1}^{K} [\,a(u_k' y) - z_k^*\,]^2$$

partial derivative w.r.t. u_{jk}:

$$\frac{\partial f(w,u;x,z^*)}{\partial u_{jk}} \;=\; 2\,[\,a(u_k'y) - z_k^*\,] \cdot a'(u_k'y) \cdot y_j$$

$$=\; 2\,[\,a(u_k'y) - z_k^*\,] \cdot a(u_k'y) \cdot (1 - a(u_k'y)) \cdot y_j$$

$$=\; \underbrace{2\,[\,z_k - z_k^*\,] \cdot z_k \cdot (1 - z_k)}_{\text{“error signal“ } \delta_k} \cdot y_j$$

partial derivative w.r.t. w_{ij}:

$$\frac{\partial f(w,u;x,z^*)}{\partial w_{ij}} \;=\; 2 \sum_{k=1}^{K} [\,\underbrace{a(u_k'y)}_{z_k} - z_k^*\,] \cdot \underbrace{a'(u_k'y)}_{z_k\,(1-z_k)} \cdot u_{jk} \cdot \underbrace{h'(w_j'x)}_{y_j\,(1-y_j)} \cdot x_i$$

$$=\; 2 \cdot \sum_{k=1}^{K} [\,z_k - z_k^*\,] \cdot z_k \cdot (1 - z_k) \cdot u_{jk} \cdot y_j\,(1 - y_j) \cdot x_i$$

factors reordered

$$=\; x_i \cdot \underbrace{y_j \cdot (1-y_j) \cdot \sum_{k=1}^{K} \underbrace{2 \cdot [\,z_k - z_k^*\,] \cdot z_k \cdot (1 - z_k)}_{\text{error signal } \delta_k \text{ from previous layer}} \cdot u_{jk}}_{\text{error signal } \delta_j \text{ from “current“ layer}}$$

Generalization (> 2 layers)

Let neural network have L layers $S_1, S_2, \ldots S_L$.
Let neurons of all layers be numbered from 1 to N.

$j \in S_m \rightarrow$ neuron j is in m-th layer

All weights w_{ij} are gathered in weights matrix W.

Let o_j be output of neuron j.

error signal:

$$\delta_j = \begin{cases} o_j \cdot (1 - o_j) \cdot (o_j - z_j^*) & \text{if } j \in S_L \text{ (output neuron)} \\ o_j \cdot (1 - o_j) \cdot \displaystyle\sum_{k \in S_{m+1}} \delta_k \cdot w_{jk} & \text{if } j \in S_m \text{ and } m < L \end{cases}$$

correction:

$$w_{ij}^{(t+1)} = w_{ij}^{(t)} - \gamma \cdot o_i \cdot \delta_j$$

<u>in case of online learning</u>:
correction after **each** test pattern presented

error signal of neuron in inner layer determined by

- error signals of all neurons of subsequent layer and
- weights of associated connections.

$\Downarrow$

- First determine error signals of output neurons,
- use these error signals to calculate the error signals of the preceding layer,
- use these error signals to calculate the error signals of the preceding layer,
- and so forth until reaching the first inner layer.

$\Downarrow$

thus, error is propagated backwards from output layer to first inner
$\Rightarrow$ **backpropagation** (of error)

⇒ other optimization algorithms deployable!

in addition to **backpropagation** (gradient descent) also:

- **Backpropagation with Momentum**
  take into account also previous change of weights:

$$\Delta w_{ij}^{(t)} = -\gamma_1 \cdot o_i \cdot \delta_j - \gamma_2 \cdot \Delta w_{ij}^{(t-1)}$$

- **QuickProp**
  assumption: error function can be approximated locally by quadratic function,
  update rule uses last two weights at step t – 1 and t – 2.

- **Resilient Propagation (RPROP)**
  exploits sign of partial derivatives:
  2 times negative or positive ⇒ increase step!
  change of sign ⇒ reset last step and decrease step!
  typical values: factor for decreasing 0,5 / factor of increasing 1,2

- **evolutionary algorithms**
  individual = weights matrix

later more about this!