## technische universität dortmund <br> Computational Intelligence

Winter Term 2019/20

- Introduction to ANN
- McCulloch Pitts Neuron (MCP)
- Minsky / Papert Perceptron (MPP)


Introduction to Artificial Neural Networks Lecture 10

Abstraction


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Lecture }1
```

Model
McCulloch-Pitts-Neuron 1943:

$$
\begin{aligned}
& x_{i} \in\{0,1\}=: \mathbb{B} \\
& \mathrm{f}: \mathbb{B}^{\mathrm{n}} \rightarrow \mathbb{B}
\end{aligned}
$$

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## 1943: Warren McCulloch / Walter Pitts

- description of neurological networks
$\rightarrow$ modell: McCulloch-Pitts-Neuron (MCP)
- basic idea:
- neuron is either active or inactive
- skills result from connecting neurons
- considered static networks
(i.e. connections had been constructed and not learnt)


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## McCulloch-Pitts-Neuron

n binary input signals $\mathrm{x}_{1}, \ldots, \mathrm{x}_{\mathrm{n}}$
threshold $\theta>0$

NOT

in addition: $m$ binary inhibitory signals $\mathrm{y}_{1}, \ldots, \mathrm{y}_{\mathrm{m}}$
$\tilde{f}\left(x_{1}, \ldots, x_{n} ; y_{1}, \ldots, y_{m}\right)=f\left(x_{1}, \ldots, x_{n}\right) \cdot \prod_{j=1}^{m}\left(1-y_{j}\right)$

- if at least one $y_{j}=1$, then output $=0$
- otherwise:
- sum of inputs $\geq$ threshold, then output $=1$

$$
\text { else output }=0
$$

## Assumption:

inputs also available in inverted form, i.e. $\exists$ inverted inputs.

## Theorem:

Every logical function $F: \mathbb{B}^{n} \rightarrow \mathbb{B}$ can be simulated with a two-layered McCulloch/Pitts net.

Example: $\quad F(x)=x_{1} x_{2} \bar{x}_{3} \vee \bar{x}_{1} \bar{x}_{2} \bar{x}_{3} \vee x_{1} \bar{x}_{4}$

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Proof: (by construction)
Every boolean function F can be transformed in disjunctive normal form
$\Rightarrow 2$ layers (AND - OR)

1. Every clause gets a decoding neuron with $\theta=\mathrm{n}$ $\Rightarrow$ output = 1 only if clause satisfied (AND gate)
2. All outputs of decoding neurons are inputs of a neuron with $\theta=1$ (OR gate)

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## Introduction to Artificial Neural Networks

Lecture 10

Generalization: inputs with weights

fires 1 if

$$
\begin{array}{r}
0,2 x_{1}+0,4 x_{2}+0,3 x_{3} \geq 0,7  \tag{10}\\
2 x_{1}+4 x_{2}+3 x_{3} \geq 7
\end{array}
$$

$\Downarrow$
$x_{3}$


$\Rightarrow$ equivalent!
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## Theorem:

Weighted and unweighted MCP-nets are equivalent for weights $\in Q^{+}$.

## Proof:

" $\Rightarrow$ "

$$
\text { Let } \sum_{i=1}^{n} \frac{a_{i}}{b_{i}} x_{i} \geq \frac{a_{0}}{b_{0}} \text { with } a_{i}, b_{i} \in \mathrm{~N}
$$

Multiplication with $\prod_{i=0}^{n} b_{i}$ yields inequality with coefficients in $\mathbb{N}$
Duplicate input $x_{i}$, such that we get $a_{i} b_{1} b_{2} \square b_{i-1} b_{i+1} \square b_{n}$ inputs.
Threshold $\theta=\mathrm{a}_{0} \mathrm{~b}_{1} \square \mathrm{~b}_{\mathrm{n}}$
" $\Leftarrow$ "
Set all weights to 1.
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## Conclusion for MCP nets

+ feed-forward: able to compute any Boolean function
+ recursive: able to simulate DFA
- very similar to conventional logical circuits
- difficult to construct
- no good learning algorithm available



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## Perceptron (Rosenblatt 1958)

$\rightarrow$ complex model $\rightarrow$ reduced by Minsky \& Papert to what is „necessary"
$\rightarrow$ Minsky-Papert perceptron (MPP), $1969 \rightarrow$ essential difference: $x \in[0,1] \subset R$

## What can a single MPP do?

$$
w_{1} x_{1}+w_{2} x_{2} \geq \theta \stackrel{\mathrm{N}}{\mathrm{~N}} 0
$$

$$
\text { isolation of } x_{2} \text { yields: }
$$

$$
x_{2} \geq \frac{\theta}{w_{2}}-\frac{w_{1}}{w_{2}} x_{1} \xlongequal{\mathrm{Y}} 0
$$

## Example:

$$
\begin{aligned}
& 0,9 x_{1}+0,8 x_{2} \geq 0,6 \\
& \Leftrightarrow \quad x_{2} \geq \frac{3}{4}-\frac{9}{8} x_{1}
\end{aligned}
$$


separating line separates $R^{2}$ in 2 classes
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## 1969: Marvin Minsky / Seymor Papert

- book Perceptrons $\rightarrow$ analysis math. properties of perceptrons
- disillusioning result:
perceptions fail to solve a number of trivial problems!

> - XOR Problem

- Parity Problem
- Connectivity Problem
- "conclusion": all artificial neurons have this kind of weakness! $\Rightarrow$ research in this field is a scientific dead end!
- consequence: research funding for ANN cut down extremely (~ 15 years)


## how to leave the „dead end":

1. Multilayer Perceptrons:

2. Nonlinear separating functions:

$$
\text { XOR } \quad g\left(x_{1}, x_{2}\right)=2 x_{1}+2 x_{2}-4 x_{1} x_{2}-1 \quad \text { with } \quad \theta=0
$$



$$
\begin{aligned}
& g(0,0)=-1 \\
& g(0,1)=+1 \\
& g(1,0)=+1 \\
& g(1,1)=-1
\end{aligned}
$$

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Introduction to Artificial Neural Networks
Lecture 10

## Perceptron Learning

Assumption: test examples with correct I/O behavior available

## Principle:

(1) choose initial weights in arbitrary manner
(2) feed in test pattern
(3) if output of perceptron wrong, then change weights
(4) goto (2) until correct output for all test paterns

## graphically:

$\rightarrow$ translation and rotation of separating lines

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## How to obtain weights $w_{i}$ and threshold $\theta$ ?

as yet: by construction
example: NAND-gate

| $x_{1}$ | $x_{2}$ | NAND |
| :---: | :---: | :---: |
| 0 | 0 | 1 |
| 0 | 1 | 1 |
| 1 | 0 | 1 |
| 1 | 1 | 0 |

$$
\begin{aligned}
& \Rightarrow 0 \geq \theta \\
& \Rightarrow \mathrm{w}_{2} \geq \theta \\
& \Rightarrow \mathrm{w}_{1} \geq \theta \\
& \Rightarrow \mathrm{w}_{1}+\mathrm{w}_{2}<\theta
\end{aligned}
$$

$$
\Rightarrow w_{2} \geq \theta \quad\langle\quad \text { requires solution of a system of }
$$

$$
\text { linear inequalities }(\in P)
$$

$$
\left(e . g .: w_{1}=w_{2}=-2, \theta=-3\right)
$$

now: by „learning" / training dortmund

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Example


$$
\begin{aligned}
& P=\left\{\binom{1}{1},\binom{1}{-1},\binom{0}{-1}\right\} \\
& N=\left\{\binom{-1}{-1},\binom{-1}{1},\binom{0}{1}\right\}
\end{aligned}
$$

threshold as a weight: $\mathrm{w}=\left(\theta, \mathrm{w}_{1}, \mathrm{w}_{2}\right)^{4}$

$$
\begin{array}{ll}
1 & -\theta \\
x_{1} & \overline{w_{1}} \\
x_{2} & \frac{\mathrm{w}_{1}}{\mathrm{w}_{2}}
\end{array}
$$

$\Downarrow$
$P=\left\{\left(\begin{array}{l}1 \\ 1 \\ 1\end{array}\right),\left(\begin{array}{r}1 \\ 1 \\ -1\end{array}\right),\left(\begin{array}{r}1 \\ 0 \\ -1\end{array}\right)\right\}$
$N=\left\{\left(\begin{array}{r}1 \\ -1 \\ -1\end{array}\right),\left(\begin{array}{r}1 \\ -1 \\ 1\end{array}\right),\left(\begin{array}{l}1 \\ 0 \\ 1\end{array}\right)\right\}$
suppose initial vector of weights is
$w^{(0)}=(1,-1,1)$

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## Perceptron Learning

 N : set of negative examples $\quad \rightarrow$ output 0 threshold $\theta$ integrated in weights1. choose $w_{0}$ at random, $t=0$
2. choose arbitrary $x \in P \cup N$
3. if $x \in P$ and $w_{t}^{\prime} x>0$ then goto 2 if $x \in N$ and $w_{t}^{\prime} x \leq 0$ then goto 2
4. if $x \in P$ and $w_{t}^{\prime} x \leq 0$ then

$$
w_{t+1}=w_{t}+x ; t++; \text { goto } 2
$$

5. if $x \in N$ and $w_{t}^{*} x>0$ then $w_{t+1}=w_{t}-\mathrm{x} ; \mathrm{t}++$; goto 2
6. stop? If I/O correct for all examples!
remark: algorithm converges, is finite, worst case: exponential runtime
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## Single-Layer Perceptron (SLP)

Lecture 10

## Generalization:

Assumption: $x \in \mathbb{R}^{n} \quad \Rightarrow\|x\|>0$ for all $x \neq(0, \ldots, 0)^{\text {c }}$
as before: $\mathrm{w}_{\mathrm{t}+1}=\mathrm{w}_{\mathrm{t}}+(\delta+\varepsilon) \mathrm{x}$ for $\varepsilon>0$ (small) and $\delta=-\mathrm{w}_{\mathrm{t}}^{\mathrm{t}} \mathrm{x}>0$

$$
\Rightarrow \mathrm{w}_{\mathrm{t}+1}^{\iota_{\mathrm{t}} \mathrm{x}=}=\underbrace{\delta\left(\|\mathrm{x}\|^{2}-1\right)}_{<0 \text { possible! }>0}+\underbrace{\varepsilon\|\mathrm{x}\|^{2}}_{>0}
$$

Idea: Scaling of data does not alter classification task (if threshold 0)!
Let $\ell=\min \{\|x\|: x \in B\}>0$
Set $\hat{x}=\frac{x}{\ell} \quad \Rightarrow$ set of scaled examples $\hat{B}$

$$
\Rightarrow\|\hat{x}\| \geq 1 \quad \Rightarrow \quad\|\hat{x}\|^{2}-1 \geq 0 \quad \Rightarrow \quad w_{t+1}^{\prime} \hat{x}>0
$$

## Single-Layer Perceptron (SLP)

## Lecture 10

## Acceleration of Perceptron Learning

Assumption: $x \in\{0,1\}^{n} \Rightarrow\|x\|=\sum_{i=1}^{n}\left|x_{i}\right| \geq 1$ for all $x \neq(0, \ldots, 0)^{\text {c }}$
Let $B=P \cup\{-x: x \in N\}$
(only positive examples)

If classification incorrect, then $w^{\prime} x<0$. $\qquad$ $\uparrow$

Consequently, size of error is just $\delta=-w^{\prime} x>0$.
$\Rightarrow \mathrm{w}_{\mathrm{t}+1}=\mathrm{w}_{\mathrm{t}}+(\delta+\varepsilon) \times$ for $\varepsilon>0$ (small) corrects error in a single step, since

$$
\mathrm{w}_{\mathrm{t}+1}^{\mathrm{s}} \mathrm{x}=\left(\mathrm{w}_{\mathrm{t}}+(\delta+\varepsilon) \mathrm{x}\right)^{\cdot} \mathrm{x}
$$

$=\underbrace{w_{t}^{\prime}} x+(\delta+\varepsilon) x^{\prime} x$
$=-\delta+\delta\|x\|^{2}+\varepsilon\|x\|^{2}$
$=\delta\left(\|x\|^{2}-1\right)+\varepsilon\|x\|^{2}>0 \quad$ $\quad \underbrace{-}$
$\underbrace{8} \underbrace{\varepsilon ـ}_{>0}$
$\geq 0 \quad>0$
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## Single-Layer Perceptron (SLP)

Lecture 10

There exist numerous variants of Perceptron Learning Methods.

## Theorem: (Duda \& Hart 1973)

If rule for correcting weights is $w_{t+1}=w_{t}+\gamma_{t} x \quad\left(\right.$ if $\left.w_{t}^{\prime} x<0\right)$

1. $\forall \mathrm{t} \geq 0: \gamma_{\mathrm{t}} \geq 0$
2. $\sum_{t=0}^{\infty} \gamma_{t}=\infty$
3. $\lim _{m \rightarrow \infty} \frac{\sum_{t=0}^{m} \gamma_{t}^{2}}{\left(\sum_{t=0}^{m} \gamma_{t}\right)^{2}}=0$
then $\mathrm{w}_{\mathrm{t}} \rightarrow \mathrm{w}^{*}$ for $\mathrm{t} \rightarrow \infty$ with $\forall \mathrm{x}: \mathrm{x}^{\mathrm{c}} \mathrm{w}^{*}>0$
e.g.: $\quad \gamma_{t}=\gamma>0$ or $\gamma_{t}=\gamma /(t+1)$ for $\gamma>0$

## Single-Layer Perceptron (SLP)

## Lecture 10

as yet: Online Learning
$\rightarrow$ Update of weights after each training pattern (if necessary)
now: Batch Learning
$\rightarrow$ Update of weights only after test of all training patterns
$\rightarrow$ Update rule:

$$
\mathrm{w}_{\mathrm{t}+1}=\mathrm{w}_{\mathrm{t}}+\gamma \sum_{\substack{w_{\mathrm{t}}^{\prime} \mathrm{x}<0 \\ \mathrm{x} \in \mathrm{~B}}} \mathrm{x} \quad(\gamma>0)
$$

vague assessment in literature:

- advantage : „usually faster"
- disadvantage : „needs more memory"
just a single vector!
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## Single-Layer Perceptron (SLP)

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## Gradient method

$w_{t+1}=w_{t}-\gamma \nabla f\left(w_{t}\right)$

$$
\begin{aligned}
& \text { Gradient points in direction of } \\
& \text { steepest ascent of function } f(\cdot)
\end{aligned}
$$

$$
\text { Gradient } \quad \nabla f(w)=\left(\frac{\partial f(w)}{\partial w_{1}}, \frac{\partial f(w)}{\partial w_{2}}, \ldots, \frac{\partial f(w)}{\partial w_{n}}\right)
$$

## Caution:

$$
\frac{\partial f(w)}{\partial w_{i}}=-\frac{\partial}{\partial w_{i}} \sum_{x \in F(w)} w^{\prime} x=-\frac{\partial}{\partial w_{i}} \sum_{x \in F(w)} \sum_{j=1}^{n} w_{j} \cdot x_{j}
$$ vector w; they are not the iteration counters!

$$
=-\sum_{x \in F(w)} \frac{\partial}{\partial w_{i}}\left(\sum_{j=1}^{n} w_{j} \cdot x_{j}\right)=-\sum_{x \in F(w)} x_{i}
$$

## Single-Layer Perceptron (SLP)

## Lecture 10

## find weights by means of optimization

Let $F(w)=\left\{x \in B: w^{\prime} x<0\right\}$ be the set of patterns incorrectly classified by weight $w$.

Objective function:

$$
f(w)=\sum_{x \in F(w)}^{-} w^{\prime} x \rightarrow \min !
$$

Optimum:

$$
f(w)=0 \quad \text { iff } F(w) \text { is empty }
$$

## Possible approach: gradient method

$$
\mathrm{w}_{\mathrm{t}+1}=\mathrm{w}_{\mathrm{t}}-\gamma \nabla \mathrm{f}\left(\mathrm{w}_{\mathrm{t}}\right) \quad(\gamma>0)
$$

converges to a local minimum (dep. on $\mathrm{w}_{0}$ )
$\square$

## Single-Layer Perceptron (SLP)

## Lecture 10

## Gradient method

thus:
gradient $\quad \nabla f(w)=\left(\frac{\partial f(w)}{\partial w_{1}}, \frac{\partial f(w)}{\partial w_{2}}, \ldots, \frac{\partial f(w)}{\partial w_{n}}\right)^{\prime}$

$$
\begin{aligned}
& =\left(\sum_{x \in F(w)} x_{1},-\sum_{x \in F(w)} x_{2}, \ldots,-\sum_{x \in F(w)} x_{n}\right)^{\prime} \\
& =-\sum_{x \in F(w)} x
\end{aligned}
$$

$$
\Rightarrow w_{t+1}=w_{t}+\gamma \sum_{x \in F\left(w_{t}\right)} x
$$

## Single-Layer Perceptron (SLP)

## Lecture 10

## How difficult is it

(a) to find a separating hyperplane, provided it exists?
(b) to decide, that there is no separating hyperplane?

Let $B=P \cup\{-x: x \in N\} \quad$ (only positive examples), $w_{i} \in \mathbb{R}, \theta \in R,|B|=m$
For every example $x_{i} \in B$ should hold:
$\mathrm{x}_{\mathrm{i} 1} \mathrm{w}_{1}+\mathrm{x}_{\mathrm{i} 2} \mathrm{w}_{2}+\ldots+\mathrm{x}_{\mathrm{in}} \mathrm{w}_{\mathrm{n}} \geq \theta \quad \rightarrow$ trivial solution $\mathrm{w}_{\mathrm{i}}=\theta=0$ to be excluded!
Therefore additionally: $\eta \in R$
$\mathrm{x}_{\mathrm{i} 1} \mathrm{w}_{1}+\mathrm{x}_{\mathrm{i} 2} \mathrm{w}_{2}+\ldots+\mathrm{x}_{\mathrm{in}} \mathrm{w}_{\mathrm{n}}-\theta-\eta \geq 0$
Idea: $\eta$ maximize $\rightarrow$ if $\eta^{*}>0$, then solution found

## Matrix notation:

$$
A=\left(\begin{array}{ccc}
x_{1}^{\prime} & -1 & -1 \\
x_{2}^{\prime} & -1 & -1 \\
\vdots & \vdots & \vdots \\
x_{m}^{\prime} & -1 & -1
\end{array}\right) \quad z=\left(\begin{array}{c}
w \\
\theta \\
\eta
\end{array}\right)
$$

## Linear Programming Problem:

$f\left(z_{1}, z_{2}, \ldots, z_{n}, z_{n+1}, z_{n+2}\right)=z_{n+2} \rightarrow \max !$
s.t. $A z \geq 0$
calculated by e.g. Kamarkaralgorithm in polynomial time

If $z_{n+2}=\eta>0$, then weights and threshold are given by $z$.
Otherwise separating hyperplane does not exist!
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