

Computational Intelligence

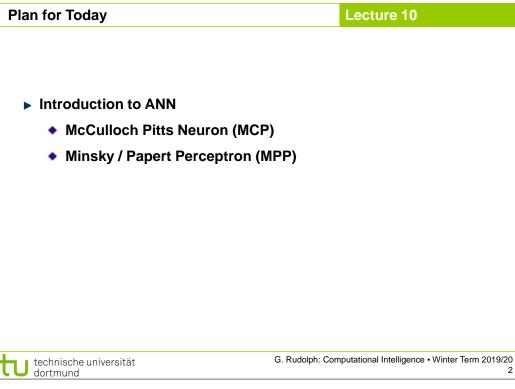
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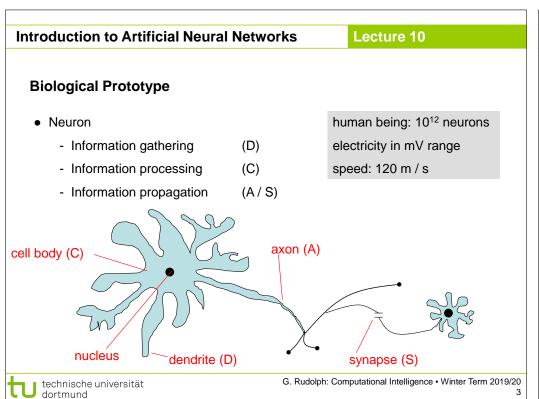
Prof. Dr. Günter Rudolph

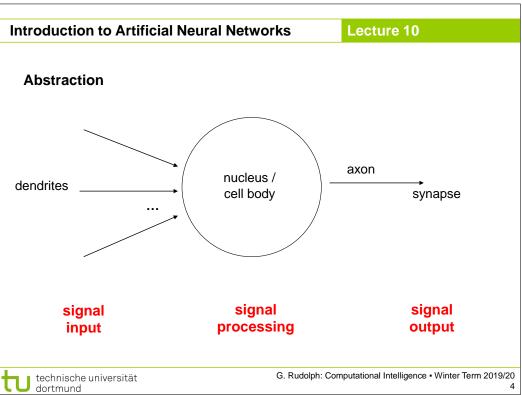
Lehrstuhl für Algorithm Engineering (LS 11)

Fakultät für Informatik

TU Dortmund

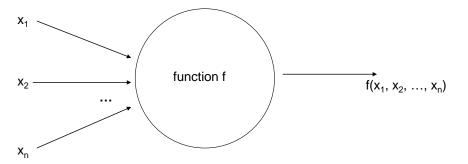






Lecture 10

Model



McCulloch-Pitts-Neuron 1943:

$$x_i \in \{\ 0,\ 1\ \} =: \mathbb{B}$$

$$f:\mathbb{B}^n \to \mathbb{B}$$



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Introduction to Artificial Neural Networks

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1943: Warren McCulloch / Walter Pitts

- description of neurological networks
 - → modell: McCulloch-Pitts-Neuron (MCP)
- basic idea:
 - neuron is either active or inactive
 - skills result from connecting neurons
- considered static networks (i.e. connections had been constructed and not learnt)



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Introduction to Artificial Neural Networks

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McCulloch-Pitts-Neuron

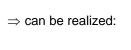
n binary input signals x₁, ..., x_n

threshold $\theta > 0$

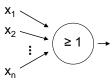
$$f(x_1, \dots, x_n) = \begin{cases} 1 & \text{if } \sum\limits_{i=1}^n x_i \ge \theta \\ 0 & \text{else} \end{cases}$$

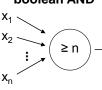
boolean OR

boolean AND



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 $\theta = 1$

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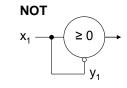
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McCulloch-Pitts-Neuron

n binary input signals $x_1, ..., x_n$

threshold $\theta > 0$

in addition: m binary inhibitory signals y₁, ..., y_m



$$\tilde{f}(x_1,\ldots,x_n;y_1,\ldots,y_m) = f(x_1,\ldots,x_n) \cdot \prod_{j=1}^m (1-y_j)$$

- if at least one y_i = 1, then output = 0
- otherwise:
 - sum of inputs ≥ threshold, then output = 1 else output = 0

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Assumption:

inputs also available in inverted form, i.e. ∃ inverted inputs.

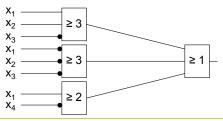


Theorem:

Every logical function $F: \mathbb{B}^n \to \mathbb{B}$ can be simulated with a two-layered McCulloch/Pitts net.

Example:

$$F(x) = x_1 x_2 \overline{x}_3 \vee \overline{x}_1 \overline{x}_2 \overline{x}_3 \vee x_1 \overline{x}_4$$



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Proof: (by construction)

Every boolean function F can be transformed in disjunctive normal form

⇒ 2 layers (AND - OR)

1. Every clause gets a decoding neuron with $\theta = n$ ⇒ output = 1 only if clause satisfied (AND gate)

2. All outputs of decoding neurons are inputs of a neuron with $\theta = 1$ (OR gate)

q.e.d.

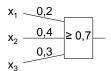
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Generalization: inputs with weights

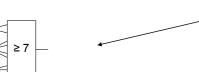


fires 1 if
$$0.2 x_1 + 0.4 x_2 + 0.3 x_3 \ge 0.7$$
 | • 10

 $2 x_1 + 4 x_2 + 3 x_3 \ge 7$

duplicate inputs!





 \Rightarrow equivalent!

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Theorem:

Weighted and unweighted MCP-nets are equivalent for weights $\in \mathbb{Q}^+$.

Proof:

,=" Let
$$\sum_{i=1}^n \frac{a_i}{b_i} x_i \geq \frac{a_0}{b_0}$$
 with $a_i,b_i \in \mathbb{N}$

Multiplication with $\ \prod \ b_i$ yields inequality with coefficients in $\mathbb N$

Duplicate input x_i , such that we get $a_i b_1 b_2 \square b_{i-1} b_{i+1} \square b_n$ inputs.

Threshold $\theta = a_0 b_1 \square b_n$

"⇐"

Set all weights to 1. technische universität

q.e.d.

Conclusion for MCP nets

- + feed-forward: able to compute any Boolean function
- + recursive: able to simulate DFA
- very similar to conventional logical circuits
- difficult to construct
- no good learning algorithm available

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Perceptron (Rosenblatt 1958)

- → complex model → reduced by Minsky & Papert to what is "necessary"
- \rightarrow Minsky-Papert perceptron (MPP), 1969 \rightarrow essential difference: $x \in [0,1] \subset \mathbb{R}$

What can a single MPP do?

isolation of x_2 yields:

Example:

$$0,9x_1+0,8x_2 \ge 0,6$$

$$\Leftrightarrow x_2 \ge \frac{3}{4} - \frac{9}{8}x_1$$



separating line

separates R²

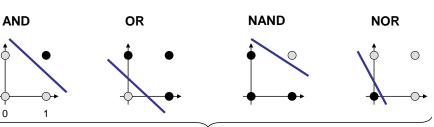
in 2 classes



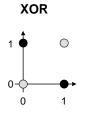
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→ MPP at least as powerful as MCP neuron!



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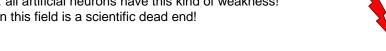
			•
X ₁	X ₂	xor	
0	0	0	$\Rightarrow 0 < \theta$ $w_1, w_2 \ge \theta > 0$
0	1	1	\Rightarrow $w_2 \ge \theta$
1	0	1	$\Rightarrow w_1 \ge \theta \qquad \qquad \Rightarrow w_1 + w_2 \ge 2\theta$
1	1	0	\Rightarrow W ₁ + W ₂ < θ
			contradiction!

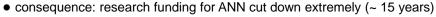
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1969: Marvin Minsky / Seymor Papert

- book *Perceptrons* → analysis math. properties of perceptrons
- disillusioning result: perceptions fail to solve a number of trivial problems!
 - XOR Problem
 - Parity Problem
 - Connectivity Problem
- "conclusion": all artificial neurons have this kind of weakness! ⇒ research in this field is a scientific dead end!



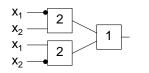




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how to leave the "dead end":

1. Multilayer Perceptrons:



⇒ realizes XOR

2. Nonlinear separating functions:

$$g(x_1, x_2) = 2x_1 + 2x_2 - 4x_1x_2 - 1$$
 with $\theta = 0$



$$g(0,0) = -1$$

$$g(0,1) = +1$$

$$g(1,0) = +1$$

$$g(1,1) = -1$$

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How to obtain weights w_i and threshold θ ?

as yet: by construction

example: NAND-gate

X ₁	X ₂	NAND
0	0	1
0	1	1
1	0	1
1	1	0

$$\Rightarrow 0 \ge \theta$$
$$\Rightarrow w_2 \ge \theta$$

$$\Rightarrow$$
 $w_1 \ge \theta$

 \Rightarrow $W_2 \ge \theta$ requires solution of a system of

⇒
$$w_1 \ge \theta$$

⇒ $w_1 + w_2 < \theta$ | linear inequalities (∈ P)
(e.g.: $w_1 = w_2 = -2$, $\theta = -3$)

now: by "learning" / training



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Perceptron Learning

Assumption: test examples with correct I/O behavior available

Principle:

- (1) choose initial weights in arbitrary manner
- (2) feed in test pattern
- (3) if output of perceptron wrong, then change weights
- (4) goto (2) until correct output for all test paterns

graphically:



→ translation and rotation of separating lines

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Example



$$P = \left\{ \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix}, \begin{pmatrix} 0 \\ -1 \end{pmatrix} \right\} \quad \bullet$$

$$N = \left\{ \begin{pmatrix} -1 \\ -1 \end{pmatrix}, \begin{pmatrix} -1 \\ 1 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right\} \quad \odot$$

threshold as a weight: $w = (\theta, w_1, w_2)$

$$\begin{array}{c|c}
1 & -\theta \\
x_1 & \hline
 & w_1 \\
x_2 & \hline
 & w_2
\end{array}
\ge 0$$

$$P = \left\{ \begin{pmatrix} 1\\1\\1 \end{pmatrix}, \begin{pmatrix} 1\\1\\-1 \end{pmatrix}, \begin{pmatrix} 1\\0\\-1 \end{pmatrix} \right\}$$

$$N = \left\{ \begin{pmatrix} 1 \\ -1 \\ -1 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} \right\}$$

suppose initial vector of weights is

$$W^{(0)} = (1, -1, 1)^{\circ}$$

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Perceptron Learning

P: set of positive examples → output 1 N: set of negative examples → output 0 threshold θ integrated in weights

- 1. choose w_0 at random, t = 0
- 2. choose arbitrary $x \in P \cup N$
- 3. if $x \in P$ and w_t 'x > 0 then goto 2 if $x \in N$ and w_t ' $x \le 0$ then goto 2
- 4. if $x \in P$ and w_t ' $x \le 0$ then $W_{t+1} = W_t + X$; t++; goto 2
- 5. if $x \in N$ and w_t 'x > 0 then $W_{t+1} = W_t - X$; t++; goto 2

Single-Layer Perceptron (SLP)

6. stop? If I/O correct for all examples!

- I/O correct!
 - let w'x \leq 0, should be > 0! (W+X)'X = W'X + X'X > W'X
 - let w'x > 0, should be \leq 0! (W-X)'X = W'X - X'X < W'X

remark: algorithm converges, is finite, worst case: exponential runtime



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Generalization:

Assumption: $x \in \mathbb{R}^n \implies ||x|| > 0$ for all $x \neq (0, ..., 0)$

as before: $w_{t+1} = w_t + (\delta + \varepsilon) x$ for $\varepsilon > 0$ (small) and $\delta = -w'_t x > 0$

$$\Rightarrow w'_{t+1}x = \delta(||x||^2 - 1) + \varepsilon ||x||^2$$

$$\leq 0 \text{ possible!} > 0$$

<u>Idea:</u> Scaling of data does not alter classification task (if threshold 0)!

Let
$$\ell = \min\{||x||: x \in B\} > 0$$

Set $\hat{x} = \frac{x}{\ell}$ \Rightarrow set of scaled examples \hat{B} $\Rightarrow \| \mathring{\mathbf{x}} \| \ge 1 \quad \Rightarrow \quad \| \mathring{\mathbf{x}} \|^2 - 1 \ge 0 \quad \Rightarrow \quad \mathbf{w'}_{t+1} \mathring{\mathbf{x}} > 0 \quad \mathbf{\square}$

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Single-Layer Perceptron (SLP)

Lecture 10

Acceleration of Perceptron Learning

Assumption:
$$x \in \{0, 1\}^n \Rightarrow ||x|| = \sum_{i=1}^n |x_i| \ge 1 \text{ for all } x ≠ (0, ..., 0)$$

Let B =
$$P \cup \{-x : x \in N\}$$

(only positive examples)

If classification incorrect, then w'x < 0. ←

Consequently, size of error is just $\delta = -w'x > 0$.

$$\Rightarrow$$
 w_{t+1} = w_t + (δ + ϵ) x for ϵ > 0 (small) corrects error in a single step, since

$$w'_{t+1}x = (w_t + (\delta + \varepsilon) x)' x$$

$$= w'_t x + (\delta + \varepsilon) x' x$$

$$= -\delta + \delta ||x||^2 + \varepsilon ||x||^2$$

$$= \delta (||x||^2 - 1) + \varepsilon ||x||^2 > 0$$

$$\geq 0 > 0$$

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Lecture 10

Single-Layer Perceptron (SLP)

There exist numerous variants of Perceptron Learning Methods.

Theorem: (Duda & Hart 1973)

If rule for correcting weights is $w_{t+1} = w_t + \gamma_t x$ (if $w_t \times v < 0$)

1.
$$\forall t \ge 0 : \gamma_t \ge 0$$

$$2. \sum_{t=0}^{\infty} \gamma_t = \infty$$

3.
$$\lim_{m \to \infty} \frac{\sum_{t=0}^{m} \gamma_t^2}{\left(\sum_{t=0}^{m} \gamma_t\right)^2} = 0$$

then $w_t \to w^*$ for $t \to \infty$ with $\forall x: x'w^* > 0$.

e.g.:
$$\gamma_t = \gamma > 0$$
 or $\gamma_t = \gamma / (t+1)$ for $\gamma > 0$

Single-Layer Perceptron (SLP)

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as yet: Online Learning

→ Update of weights after each training pattern (if necessary)

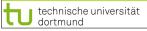
now: Batch Learning

- → Update of weights only after test of all training patterns
- → Update rule:

$$W_{t+1} = W_t + \gamma \sum_{\substack{w'_t x < 0 \\ x \in B}} x \qquad (\gamma > 0)$$

vague assessment in literature:

- advantage : "usually faster"



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Caution:
Indices i of w_i
here denote
components of
vector w; they are

not the iteration counters!

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Gradient method

Single-Layer Perceptron (SLP)

Gradient points in direction of $w_{t+1} = w_t - \gamma \nabla f(w_t)$ steepest ascent of function $f(\cdot)$

Gradient
$$\nabla f(w) = \left(\frac{\partial f(w)}{\partial w_1}, \frac{\partial f(w)}{\partial w_2}, \dots, \frac{\partial f(w)}{\partial w_n}\right)$$

$$\frac{\partial f(w)}{\partial w_i} = -\frac{\partial}{\partial w_i} \sum_{x \in F(w)} w'x = -\frac{\partial}{\partial w_i} \sum_{x \in F(w)} \sum_{j=1}^n w_j \cdot x_j$$

$$= -\sum_{x \in F(w)} \underbrace{\frac{\partial}{\partial w_i} \left(\sum_{j=1}^n w_j \cdot x_j \right)}_{x \cdot} = -\sum_{x \in F(w)} x_i$$

Single-Layer Perceptron (SLP)

Lecture 10

find weights by means of optimization

Let $F(w) = \{ x \in B : w \le 0 \}$ be the set of patterns incorrectly classified by weight w.

Objective function:
$$f(w) = -\sum_{x \in F(w)} w'x \rightarrow min!$$

Optimum:
$$f(w) = 0$$
 iff $F(w)$ is empty

Possible approach: gradient method

$$\mathbf{w}_{\mathsf{t+1}} = \mathbf{w}_{\mathsf{t}} - \gamma \; \nabla f(\mathbf{w}_{\mathsf{t}}) \qquad (\gamma > 0)$$

converges to a <u>local</u> minimum (dep. on w₀)

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Single-Layer Perceptron (SLP)

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Gradient method

thus:

gradient
$$\nabla f(w) = \left(\frac{\partial f(w)}{\partial w_1}, \frac{\partial f(w)}{\partial w_2}, \dots, \frac{\partial f(w)}{\partial w_n}\right)'$$

$$= \left(\sum_{x \in F(w)} x_1, -\sum_{x \in F(w)} x_2, \dots, -\sum_{x \in F(w)} x_n\right)'$$

$$= -\sum_{x \in F(w)} x$$

$$\Rightarrow w_{t+1} = w_t + \gamma \sum_{x \in F(w_t)} x$$

 $gradient \ method \Leftrightarrow batch \ learning$



Single-Layer Perceptron (SLP)

Lecture 10

How difficult is it

- (a) to find a separating hyperplane, provided it exists?
- (b) to decide, that there is no separating hyperplane?

Let B = P
$$\cup$$
 {-x : x \in N } (only positive examples), w_i \in R , $\theta \in$ R , |B| = m

For every example $x_i \in B$ should hold:

$$x_{i1} w_1 + x_{i2} w_2 + ... + x_{in} w_n \ge \theta$$
 \rightarrow trivial solution $w_i = \theta = 0$ to be excluded!

Therefore additionally: $\eta \in \mathbb{R}$

$$x_{i1} W_1 + x_{i2} W_2 + ... + x_{in} W_n - \theta - \eta \ge 0$$

Idea: η maximize \rightarrow if $\eta^* > 0$, then solution found



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Single-Layer Perceptron (SLP)

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Matrix notation:

$$A = \begin{pmatrix} x'_1 & -1 & -1 \\ x'_2 & -1 & -1 \\ \vdots & \vdots & \vdots \\ x'_m & -1 & -1 \end{pmatrix} \quad z = \begin{pmatrix} w \\ \theta \\ \eta \end{pmatrix}$$

Linear Programming Problem:

$$f(z_1, z_2, ..., z_n, z_{n+1}, z_{n+2}) = z_{n+2} \rightarrow max!$$

s.t. $Az \ge 0$ calculated by e.g. Kamarkar-algorithm in **polynomial time**

If $z_{n+2} = \eta > 0$, then weights and threshold are given by z.

Otherwise separating hyperplane does not exist!

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